Combining Density Forecasts via Information Aggregation Mechanism Discussion of Gillen, Plott, and Shum (2014)

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December 5, 2014

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Background

- Forecast Combination
 - Model-based: variance-covariance, regression
 - Survey-based
 - Market-based
- More info -> better forecast: Wisdom of the crowds!

Summary

• Information Aggregation Mechanism (IAM)

- Combine density forecasts
- Innovative designs
- Theory
 - "A trip to Bayesland" (Nate Silver)
 - Density forecast: Dirichlet process
- Evaluation
 - Difficulty in density forecast
 - Problem: iid?

Information Aggregation Mechanism (IAM)

- Parimutuel-like betting mechanism (vs A-D security market)
 - +: Easy and intuitive to implement
 - -: Discrepency in the ideal and actual loss functions
- Fake money
 - +: Reduce the impact of risk aversion
- Non-tradable tickets
 - +: Reduce price speculation and transaction cost
- Tickets prices increase over time
 - +: Reduce information externality
 - -: Reduce information available
- Participants are chosen to be "insiders"
 - +: Reduce self-selection bias and noise trading
 - -: Maybe some "outsiders" would help too?
 - ★ More independent info set, wisdom of the crowds

Information Aggregation Mechanism (IAM)

- Between survey- and market- based forecast combinations
 - Provide money incentive
 - But with non-tradable tickets and less self-selection problem

Theory

- "A trip to Bayesland" (Nate Silver)
 - Individual:

ind posterior = common prior + ind private info = ind ticket placement

Aggregate:

 $\begin{array}{l} \mathrm{agg \ posterior} = \mathrm{common \ prior} + \mathrm{sum \ of \ private \ info} \\ = \mathrm{agg \ ticket \ placement} \end{array}$

- More info -> better forecast
- Bayesian updating vs invisible hand

Theory

- Density forecast: Dirichlet process
 - ► A set of bins

$$P(Y \in bin k) = \pi_k$$

Prior:

$$\pi \sim \text{Dir}(\alpha_1, \cdots, \alpha_K), \ \text{E}[\pi_k] = rac{lpha_k}{\sum_{j=1}^K lpha_j}$$

Ind posterior = ind ticket placement:

$$\pi | s_n \sim Dir \left(\alpha_1 + m_n \hat{p}_{n,1}, \cdots, \alpha_K + m_n \hat{p}_{n,K} \right)$$
$$E \left[\pi_k | s_n \right] = \frac{\alpha_k + m_n \hat{p}_{n,k}}{m_n + \sum_{j=1}^K \alpha_j}$$

Agg posterior = agg ticket placement:

$$\pi | s_{1:N} \sim Dir\left(\alpha_1 + \sum_{n=1}^N m_n \hat{p}_{n,1}, \cdots, \alpha_K + \sum_{n=1}^N m_n \hat{p}_{n,K}\right)$$
$$E\left[\pi_k | s_{1:N}\right] = \frac{\alpha_k + \sum_{n=1}^N m_n \hat{p}_{n,k}}{\sum_{n=1}^N m_n + \sum_{n=1}^N \sum_{j=1}^K \alpha_j}$$

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Theory

- Some tests of the Bayesian updating in real world
 - "Belief Updating among College Students: Evidence from Experimental Variation in Information", Wiswall and Zafar (2011)
 - •

- Q: whether it accurately reflects the uncertainty in sales?
 - ► H₀: As the forecasting horizon h decreases, density forecast should get closer to the true conditional distribution of Y_t|F_{t,t-h}.
 - How to test?
- Difficulties in evaluating density forecast
 - ▶ the true conditional distribution of $Y_t | \mathcal{F}_{t,t-h}$ is not observable, even ex-post

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heterogeneous info set for different period t

- Probablity integral transformation (1-step-ahead):
 - true conditional distribution of $Y_t | \mathcal{F}_{t,t-1}$: $f_t(y_t)$
 - density forecast of $Y_t | \mathcal{F}_{t,t-1}$: $p_t(y_t) = MN(\tilde{\eta}_{1|t-1}, \cdots, \tilde{\eta}_{K|t-1})$
 - cdf of density forecast:

$$z_{t} = \int_{-\infty}^{y_{t}} p_{t}\left(\tilde{y}_{t}\right) d\tilde{y}_{t} = P_{t}\left(y_{t}\right)$$
$$\sim \frac{f_{t}\left(P_{t}^{-1}\left(z_{t}\right)\right)}{p_{t}\left(P_{t}^{-1}\left(z_{t}\right)\right)}$$
$$z_{t} \sim \frac{iid}{U}\left[0, 1\right], \text{ if } p_{t}\left(\cdot\right) = f_{t}\left(\cdot\right)$$

QQ plot, KS test

- Joint test of *iid* and U[0,1]
- but for h-step-ahead forecast, *iid* would be violated...



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- h-step-ahead Forecast
 - Recall that optimal point forecast errors MA(h-1)
 - ➤ Similarly, if the density forecast is optimal, the z_t series would be (h-1)-dependent
 - And the sub-series will be *iid*: $\{z_1, z_{1+h}, z_{1+2h}, \dots\}$, $\{z_2, z_{2+h}, z_{2+2h}, \dots\}$, $\dots, \{z_h, z_{2h}, z_{3h}, \dots\}$

- Q: whether it accurately reflects the uncertainty in sales?
 - ► H_0 : As the forecasting horizon *h* decreases, density forecast should get closer to the true conditional distribution of $Y_t | \mathcal{F}_{t,t-h}$.
- Cannot be directly compared via KS test due to serial correlation
- Maybe just compare the predictive likelihood

$$P_{h} = \prod_{t=1}^{T} p_{t|t-h}(y_{t})$$

and P_h should decrease with h