Assessing Point Forecast Accuracy by Stochastic Error Distance

> Francis X. Diebold and Minchul Shin University of Pennsylvania

> > November 15, 2014

Point Forecast Accuracy Comparison

Traditional:

Error: $e = v - \hat{v}$

Loss: $L(e)$, where $L(0) = 0$ and $L(e) \geq 0$, $\forall e$

Expected loss: $E(L(e))$, e.g. $E(e^2)$

This Paper:

We assess by comparing $F(e)$, the c.d.f. of e, and $F^*(e)$, where

$$
\digamma^*(e) = \left\{ \begin{array}{ll} 0, & e < 0 \\ 1, & e \geq 0. \end{array} \right.
$$

Stochastic Error Distance (SED)

Example: Two Forecast Error Distributions

Under the *SED* criterion, we prefer F_1 to F_2 .

SED and Expected Absolute Loss

$$
SED(F, F^*) = \int_{-\infty}^{\infty} |F(e) - F^*(e)| \, de
$$

Proposition (Equivalence of *SED* and Expected Absolute Loss):

If e is a forecast error with cumulative distribution function $F(e)$, such that $E(|e|) < \infty$, then SED equals expected absolute loss:

$$
SED(F, F^*) = E(|e|).
$$

Weighted Stochastic Error Distance (WSED)

$$
\mathsf{WSED}(F, F^*; \tau) = 2(1-\tau)\mathsf{SED}(F, F^*)_- + 2\tau \mathsf{SED}(F, F^*)_+,
$$
\n
$$
\text{where } \tau \in [0, 1].
$$

WSED and Expected Lin-Lin Loss

Proposition (Equivalence of *WSED* and Expected Lin-Lin Loss):

If e is a forecast error with cumulative distribution function $F(e)$, such that $E(|e|) < \infty$, then WSED equals expected lin-lin loss:

$$
\begin{aligned} \textit{WSED}(F, F^*; \tau) &= 2(1-\tau) \int_{-\infty}^0 F(e) \, de + 2\tau \int_0^\infty [1 - F(e)] \, de \\ &= 2E(L_\tau(e)), \end{aligned}
$$

where $L_{\tau}(e)$ is the lin-lin loss function

$$
L_{\tau}(e) = \begin{cases} (1-\tau)|e|, & e < 0\\ \tau|e|, & e \geq 0. \end{cases}
$$

Generalized Weighted Stochastic Error Distance (GWSED)

$$
GWSED(F, F^*; p, w) = \int |F(e) - F^*(e)|^p w(e) de,
$$

where $p > 0$.

SED and WSED are nested special cases:

$$
\blacktriangleright p = 1 \text{ and } w(e) = 1 \ \forall \ e \text{ produces } SED.
$$

$$
\triangleright \rho = 1 \text{ and}
$$
\n
$$
w(e) = \begin{cases} 2(1-\tau), & e < 0 \\ 2\tau, & e \ge 0 \end{cases}
$$

produces WSED.

 \triangleright Other choices of p and $w(e)$?

GWSED and Expected Loss: A Complete Characterization

$$
GWSED(F, F^*; p, w) = \int |F(e) - F^*(e)|^p w(e) de
$$

Proposition (Equiv. of *GWSED* $(F, F^*; 1,$ dL(e) $\frac{L(e)}{de}\Bigg|$) and $E(L(e))$:

Suppose that $L(e)$ is piecewise differentiable with $dL(e)/de > 0$ for $e > 0$ and $dL(e)/de < 0$ for $e < 0$, and suppose also that $F(e)$ and L(e) satisfy $F(e)L(e) \rightarrow 0$ as $e \rightarrow -\infty$ and $(1 - F(e))L(e) \rightarrow 0$ as $e \rightarrow \infty$. Then:

$$
\int_{-\infty}^{\infty} |F(e) - F^*(e)| \left| \frac{dL(e)}{de} \right| de = E(L(e)).
$$

Connections: Cramér-von Mises Divergence

 $GWSED(F, F^*; 2, f(e))$ is Cramér-von Mises divergence, $CVM(F^*, F)$:

$$
CVM(F^*, F) = \int |F^*(e) - F(e)|^2 f(e) de
$$

= $-F(0)(1 - F(0)) + \frac{1}{3}$
 $\ge \frac{1}{12}$,

where equality holds if and only if $F(0) = \frac{1}{2}$.

Hence, like $SED(F, F^*)$, $CVM(F^*, F)$ ranks forecasts according to expected absolute error.

Connections: Kolmogorov-Smirnov Distance

$$
KS(F, F^*) = \sup_e |F(e) - F^*(e)| = max (F(0), 1 - F(0)),
$$

where the lower bound is achieved at $F(0) = \frac{1}{2}$ as in the $CVM(F^*,F)$ case.

Hence, like $SED(F, F^*)$ and $CVM(F^*, F)$, $KS(F, F^*)$ ranks forecasts according to expected absolute error.

We have:

1. Stayed within the $E(L)$ framework (there is no escaping). \checkmark

- 1. Stayed within the $E(L)$ framework (there is no escaping). \checkmark
- 2. Established (surprising) primacy of absolute and lin-lin loss. \checkmark

- 1. Stayed within the $E(L)$ framework (there is no escaping). \checkmark
- 2. Established (surprising) primacy of absolute and lin-lin loss. \checkmark
- 3. Clarified what it means to "select a loss function." \checkmark

- 1. Stayed within the $E(L)$ framework (there is no escaping). \checkmark
- 2. Established (surprising) primacy of absolute and lin-lin loss. \checkmark
- 3. Clarified what it means to "select a loss function." \checkmark
- 4. Built bridges to CVM divergence, KS distance, etc. \checkmark

- 1. Stayed within the $E(L)$ framework (there is no escaping). \checkmark
- 2. Established (surprising) primacy of absolute and lin-lin loss. \checkmark
- 3. Clarified what it means to "select a loss function." \checkmark
- 4. Built bridges to CVM divergence, KS distance, etc. $\sqrt{ }$
- 5. Raised important related questions. \checkmark

Question: When Do MAE and MSE Rankings Diverge?

Simplest Gaussian environment:

$$
e \sim N\left(\mu, \sigma^2\right)
$$

$$
\implies E(|e|) = \sigma \sqrt{2/\pi} \exp\left(-\frac{\mu^2}{2\sigma^2}\right) + \mu \left[1 - 2\Phi\left(-\frac{\mu}{\sigma}\right)\right]
$$

Unbiased case ($\mu = 0$): $E(|e|) \propto \sigma$ MAE and MSE rankings must be identical

Biased case $(e_1 \sim N(0, 1)$ and $e_2 \sim N(\mu_2, \sigma_2^2)$): MAE and MSE rankings can diverge, even under normality!

MSE and MAE Divergence Regions, Gaussian Case

 $e_1 \sim \mathcal{N}(0,1)$, $e_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$ We show divergence regions in black.

